

Lecture 15: Composition of linear transformations and matrix multiplication ^①

Last time:

[§2.3 of
FIS]

$T: V \rightarrow W$ linear transformation

$\beta = \{v_1, \dots, v_n\}$ a basis for V

$\gamma = \{w_1, \dots, w_m\}$ a basis for W

$$[T]_{\beta}^{\gamma} = \begin{pmatrix} | & & | \\ [T(v_1)]_{\gamma} & \cdots & [T(v_n)]_{\gamma} \\ | & & | \end{pmatrix} \in M_{m \times n}(\mathbb{R})$$

_____ ◦ _____

Notes: • For $T: V \rightarrow V$, we'll write $[T]_{\beta}$ for $[T]_{\beta}^{\beta}$.

• For vector spaces V and W , set

$$\mathcal{L}(V, W) = \{T: V \rightarrow W \mid T \text{ linear}\}$$

and

$$\mathcal{L}(V) = \mathcal{L}(V, V).$$

Fun Fact: $\mathcal{L}(V, W)$ is itself a vector space,

~~with~~ specifically a subspace of $\mathcal{F}(V, W)$.

Come back to later, but for now details are in
the text.

(2)

Consider two linear transformations:

$$X \xrightarrow{S} Y \xrightarrow{T} Z$$

Thm: Their composition $T \circ S: X \rightarrow Z$, defined by $(T \circ S)(x) = T(S(x))$, is also a linear trans.

Pf: Suppose $x_1, x_2 \in X$, $a \in \mathbb{R}$. Then

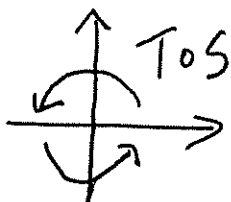
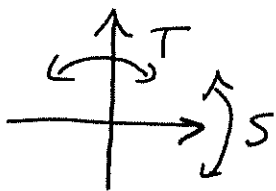
$$\begin{aligned} (T \circ S)(ax_1 + x_2) &= T(S(ax_1 + x_2)) \\ &= T(aS(x_1) + S(x_2)) = aT(S(x_1)) + T(S(x_2)) \\ &= a(T \circ S)(x_1) + (T \circ S)(x_2). \end{aligned}$$

Ex: $S, T: V \rightarrow V$ where $V = \mathbb{R}^2$ □

$S(x, y) = (-x, y)$ reflection in y -axis

$T(x, y) = (x, -y)$ reflection in x -axis

$(T \circ S)(x, y) = (-x, -y)$ rotation by angle π .



$\alpha = \{x_1, \dots, x_n\}$ basis for X

$\beta = \{y_1, \dots, y_m\}$ basis for Y

$\gamma = \{z_1, \dots, z_p\}$ basis for Z

Q: How is $[T \circ S]_{\alpha}^{\gamma}$ related to $[S]_{\alpha}^{\beta}$ and $[T]_{\beta}^{\gamma}$?

[Answer involves matrix multiplication...]

Def: Let A be a $p \times m$ matrix and B be an $m \times n$ matrix.

Then their product AB is ^{the $p \times n$ matrix} defined by

$$(AB)_{ij} = \sum_{k=1}^m A_{ik} B_{kj}$$

Ex:
$$\begin{pmatrix} 1 & 0 & 2 \\ 0 & 3 & 4 \end{pmatrix} \begin{pmatrix} 1 & -3 \\ 0 & 1 \\ 2 & 1 \end{pmatrix} = \begin{pmatrix} 5 & -1 \\ 8 & 7 \end{pmatrix}$$

$$\begin{matrix} 2 \times 3 & 3 \times 2 & 2 \times 2 \\ = & = & = \end{matrix}$$

If we view a column vector as a $m \times 1$ matrix, this agrees with the product of (matrix)(vector) defined last time.

Moreover

$$AB = A \left(\begin{array}{c|c|c} | & & | \\ b_1 & \dots & b_n \\ | & & | \end{array} \right) = \left(\begin{array}{c|c|c} | & & | \\ Ab_1 & \dots & Ab_n \\ | & & | \end{array} \right)$$

Thm: $[T \circ S]_{\alpha}^{\gamma} = [T]_{\beta}^{\gamma} [S]_{\alpha}^{\beta}$

$p \times n \qquad p \times m \qquad m \times n$

Pf: Recall from last time that if $y \in Y$ then

$$[T(y)]_{\gamma} = [T]_{\beta}^{\gamma} [y]_{\beta}$$

Now

$$[S]_{\alpha}^{\beta} = \left(\begin{array}{c|c|c} | & & | \\ [S(x_1)]_{\beta} & \dots & [S(x_n)]_{\beta} \\ | & & | \end{array} \right)$$

so

~~$$[T]_{\beta}^{\gamma} [S]_{\alpha}^{\beta} = \left(\begin{array}{c|c|c} | & & | \\ [T]_{\beta}^{\gamma} [S(x_i)]_{\beta} & & | \end{array} \right)$$~~

$$= \left(\begin{array}{c|c|c} | & & | \\ [T(S(x_i))]_{\gamma} & & | \end{array} \right) = \left(\begin{array}{c|c|c} | & & | \\ [(T \circ S)(x_i)]_{\gamma} & & | \end{array} \right)$$

$i = 1, \dots, n \qquad i = 1, \dots, n$

$$= [T \circ S]_{\alpha}^{\gamma} \quad \square$$

Ex: $S, T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ $\beta = \{e_1, e_2\}$

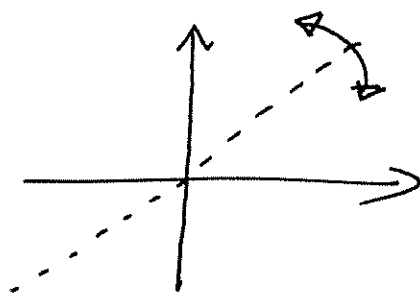
(5)

$$T(x, y) = (x, -y) \quad [T]_{\beta} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$S(x, y) = (y, x) \quad [S]_{\beta} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

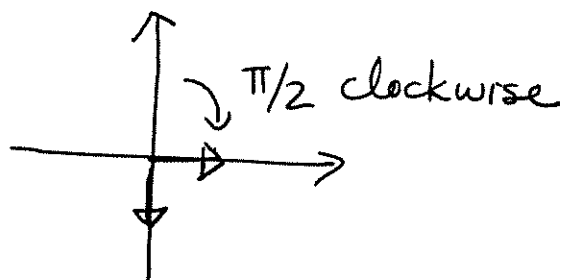
T is reflection in x -axis

S is reflection in $y=x$.



$$(T \circ S)(x, y) = T(S(x, y)) = T(y, x) = (y, -x)$$

$$[T \circ S]_{\beta} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$



$$[T]_{\beta} [S]_{\beta} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \checkmark$$

Important: Order of composition matters!

$$[S \circ T]_{\beta} = [S]_{\beta} [T]_{\beta} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

So $S \circ T$ is rotation by $\pi/2$ counter-clockwise.

Thm: Matrix multiplication is

Associative: $A(BC) = (AB)C$

Distributive: $A(B+C) = AB + AC$

$(A+B)C = AC + BC$

but not always commutative, as we just saw.

[Can prove this mechanically using formula for matrix mult. Will discuss a conceptual proof next time, but can also see the text.]

Suppose A is an $m \times n$ matrix. Then

$$A \cdot \begin{pmatrix} 0 & \dots & 0 \\ \vdots & & \vdots \\ 0 & \dots & 0 \end{pmatrix}_{n \times p} = \begin{pmatrix} 0 & \dots & 0 \\ 0 & \dots & 0 \end{pmatrix}_{m \times p}$$

$$\begin{pmatrix} 0 & \dots & 0 \\ \vdots & & \vdots \\ 0 & \dots & 0 \end{pmatrix}_{p \times m} A = \begin{pmatrix} 0 & \dots & 0 \\ \vdots & & \vdots \\ 0 & \dots & 0 \end{pmatrix}_{p \times n}$$

What about I ?

$$\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$$

Will start here next time...