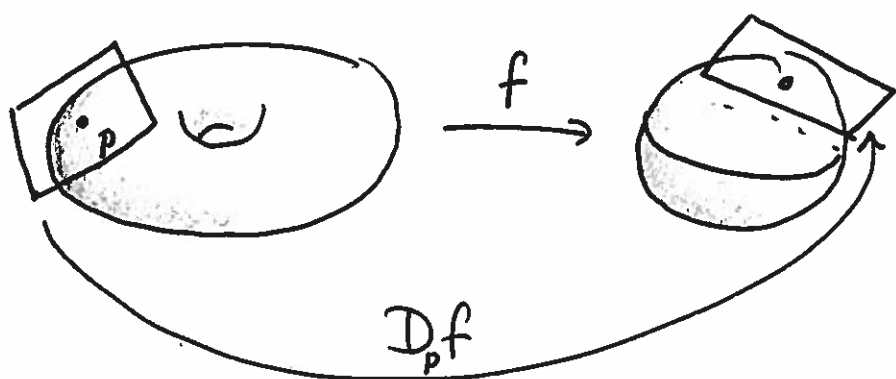


Lecture 4: Tangent spaces.

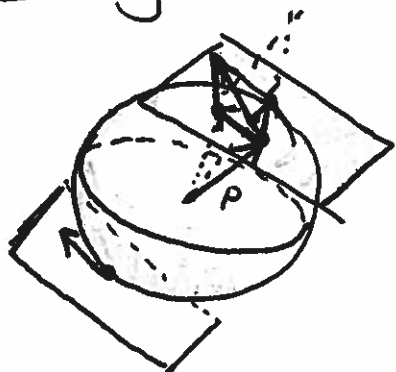
Goal: For a smooth $f: M \rightarrow N$ of smooth mflds

define vector spaces $T_p M$ and $T_{f(p)} N$ with a



linear transformation $D_p f$ approximating f near p .

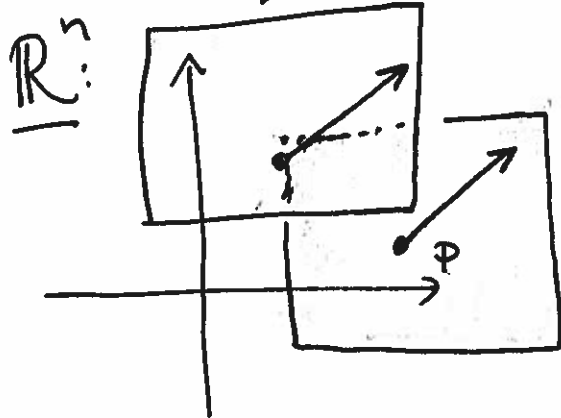
Motivating example: $S^2 = \{p \in \mathbb{R}^3 \mid |p| = 1\}$



$$T_p S^2 = \text{plane tangent to } S^2 \text{ at } p = \{x \in \mathbb{R}^3 \mid (x-p) \cdot p = 0\}$$

$$\stackrel{\text{kinda}}{=} \{x \cdot p = 0\}$$

but not really

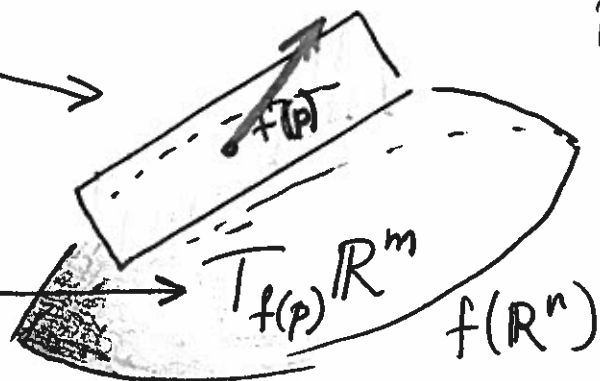


[In Math 241, these are equal.]
NO MORE!

$$T_p \mathbb{R}^n = \{p\} \times \mathbb{R}^n = \{(p, v) \mid v \in \mathbb{R}^n\}$$

$f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ smooth

$$D_p f = \left[\frac{\partial f_i}{\partial x_j} \right] : T_p \mathbb{R}^n \rightarrow T_{f(p)} \mathbb{R}^m$$



Note this still ~~works~~ makes sense:

(2)

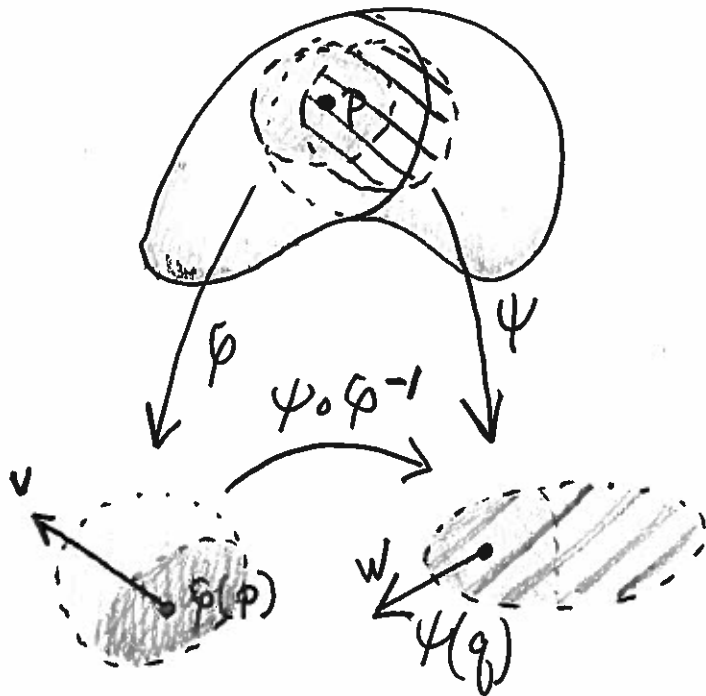
$$f(\underbrace{p+v}_{\substack{\text{pt } \mathbb{R}^n \\ \uparrow \\ T_p \mathbb{R}^n}}) = \underbrace{f(p)}_{\mathbb{R}^m} + \underbrace{D_p f(v)}_{\in T_{f(p)} \mathbb{R}^m} + \underbrace{\text{Error}_p(v)}_{O(|v|^2)}$$

Tangent vectors to a smooth $M: (p, U, \varphi, v)$

where (U, φ) is a smooth chart with $p \in U$ and $v \in T_{\varphi(p)} \mathbb{R}^n$, up to the following

equivalence: $(p, U, \varphi, v) \sim (q, V, \psi, w)$

if $p = q$ and $D_{\varphi(p)}(\psi \circ \varphi^{-1})(v) = w$.



$T_p M =$ set of such (p, U, φ, v)

Note we can add such

$$(p, U, \varphi, v_1) + (p, U, \varphi, v_2)$$

$$= (p, U, \varphi, v_1 + v_2)$$

at least when (U, φ) match.

Makes sense beyond this since $D_{\varphi(p)}(\psi \circ \varphi^{-1})$ is

a linear transformation.

(3)

Prop: For (U, φ) the map $T_{\varphi(p)} \mathbb{R}^n \rightarrow T_p M$
is an isomorphism of vector spaces. $v \mapsto (p, \varphi, U, v)$

[Pf. Basically like #4 on HW.] [But there's another way...]
[Query: How many different

Back to \mathbb{R}^n : f smooth $\mathbb{R}^n \rightarrow \mathbb{R}$
 $v \in T_a \mathbb{R}^n$

ways can you think of a deriv. fm of 1-var?



$$\text{Directional derivative of } f \text{ along } v \text{ at } a = \left. \frac{d}{dt} f(a+tv) \right|_{t=0}$$

$$= (\nabla f(a)) \cdot v$$

$$= (D_a f)(v) \quad [\text{Ex: } \partial/\partial x_i]$$

Set $C^\infty(\mathbb{R}^n) = \{ \text{smooth } f: \mathbb{R}^n \rightarrow \mathbb{R} \}$

Have $D_{v_a}: C^\infty(\mathbb{R}^n) \rightarrow \mathbb{R}$

$$f \mapsto (D_a f)(v)$$

Vector space \mathbb{R}

Properties: $\forall f, g \in C^\infty(\mathbb{R}^n)$ and $c \in \mathbb{R}$

(4)

$$\textcircled{a} D_{v_a}(cf + g) = c D_{v_a}f + D_{v_a}g$$

$$\textcircled{b} D_{v_a}(f \cdot g) = \cancel{f} (D_{v_a}f) \cdot g(a) + f(a) (D_{v_a}g)$$

[Idea: \textcircled{a} and \textcircled{b} characterize directional der.]

A map $w: C^\infty(\mathbb{R}) \rightarrow \mathbb{R}$ is a derivation ~~at~~ at a if

$$\textcircled{a} w(cf + g) = cw(f) + w(g) \quad (\mathbb{R}\text{-linear})$$

$$\textcircled{b} w(fg) = w(f)g(a) + f(a)w(\cancel{g})$$

for all $f, g \in C^\infty(\mathbb{R})$ and $c \in \mathbb{R}$.

Prop: $\mathcal{D}_a = \{ \text{set of derivations at } a \}$

The map $T_a \mathbb{R}^n \rightarrow \mathcal{D}_a$ is an isomorphism

$$v_a \longmapsto D_{v_a}$$

of \mathbb{R} -vector spaces.

[Say why this will be help full]

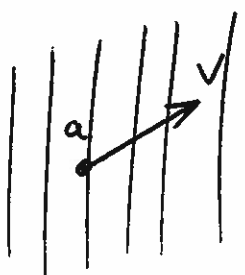
Pf: That this is a linear transformation of \mathbb{R} -vector spaces follows from

$$D_{v_a + c w_a} f = D_{v_a} f + c D_{w_a} f$$

1-1: Suppose $v_a \mapsto \begin{pmatrix} \text{const} \\ 0 \end{pmatrix}$ derivation. If

$v_i \neq 0$ then $D_{v_a} x_i \neq 0$. So ~~also~~ $v = 0$

i^{th} coord.



Point: $D_{v_a} x_i = (\nabla x_i) \cdot v$
 $= e_i \cdot \frac{v}{\sqrt{\dots}} = v_i$

onto: Let $w \in \mathcal{D}_a$. Set $v_i = w(x_i)$ and consider $v \in T_a \mathbb{R}^n$. Claim: $D_v = w$.

Suppose $f \in C^\infty(\mathbb{R}^n)$. Then

$$\frac{1}{2} \int_0^1 (1-t)^2 \frac{\partial^2}{\partial x_i \partial x_j} f(a+tx) dt$$

$$\begin{aligned} f(x) &= f(a) + (D_a f)(x-a) + \text{Error} \\ &= f(a) + \sum_i \frac{\partial f}{\partial x_i}(a)(x_i - a_i) + \sum_{ij} (x_i - a_i)(x_j - a_j) E_{ij}(x) \end{aligned}$$

$E_{ij}(x)$
smooth fn.

$$\text{Now } w(1) = w(1 \cdot 1) = w(1) \cdot 1 + 1 \cdot w(1) = 2w(1) \quad (6)$$
$$\Rightarrow w(\text{const}) = 0$$

If g & h both vanish at a , then

$$w(g \cdot h) = 0.$$

$$\text{So } w(f) = 0 + \sum \frac{\partial f}{\partial x_i}(a) (w(x_i) - 0) + 0$$
$$= \sum \frac{\partial f}{\partial x_i}(a) v_i = \nabla f(a) \cdot v = D_{v_a} f.$$

So $f \mapsto w$ as needed 