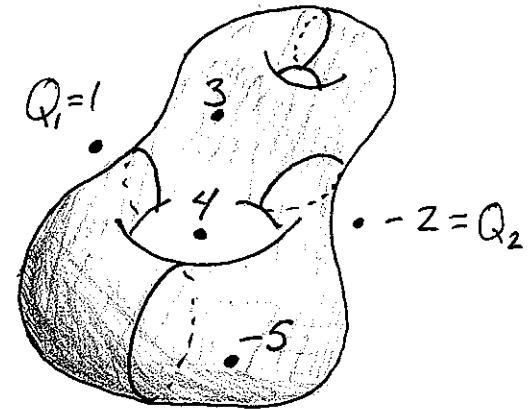


Lecture 43: Maxwell's Equations

Last time: Charges Q_i at positions \vec{p}_i

$$\vec{E}(\vec{r}) = \sum \frac{Q_i}{4\pi\epsilon_0} \frac{1}{|\vec{r}-\vec{p}_i|^3} (\vec{r}-\vec{p}_i)$$



Gauss's Law: D a region in \mathbb{R}^3

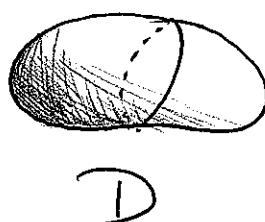
$$\iint_D (\vec{E} \cdot \hat{n}) dA = \frac{1}{\epsilon_0} (\text{Total charge in } D)$$

$$\text{Flux} = \frac{-2}{\epsilon_0}$$

[On HW for today, used this compute the total charge from a formula for \vec{E} . This is not impractical...]

When there are many (e.g. 10^{20}) can't use ~~use~~ the formula for \vec{E} directly. Don't want to focus on each charge individually just as we don't count molecules when measuring the mass.

Mass: $\rho(x, y, z)$ mass density, units = $\frac{\text{g}}{\text{m}^3}$

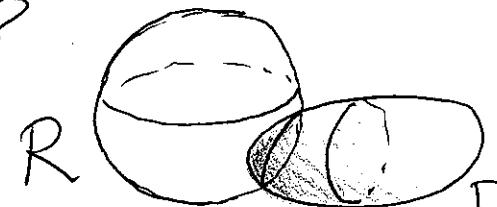


$$\text{Total Mass} = \iiint_D \rho dV$$

Charge: $\rho(x, y, z)$ charge density, units = $\frac{\text{coulomb}}{\text{m}^3}$

$$\text{Total Charge} = \iiint_D \rho dV$$

Q: How does ρ determine \vec{E} ?



Gauss's Law should still hold, so for a region R we have

$$\frac{1}{\epsilon_0} (\text{Charge in } R) = \iint_{\partial R} (\vec{E} \cdot \hat{n}) dA = \iiint_R \operatorname{div} \vec{E} dV$$

↑
Divergence Thm

$$\frac{1}{\epsilon_0} \iiint_R \rho dV$$

As true for all regions R , must have $\operatorname{div} \vec{E} = \frac{\rho}{\epsilon_0}$

[Q:] Does this answer the question? Not completely since many vector fields have the same divergence.

A. $\vec{E}(r) = (E_1(r), E_2(r), E_3(r))$ where if $r = (a, b, c)$

then

$$E_1(r) = \frac{1}{4\pi\epsilon_0} \iiint_D \frac{(a-x)\rho(x,y,z)}{|r-(x,y,z)|^3} dV$$

etc.

Exercise: Take $D = \text{unit sphere}$ and $\rho = 1$.

Use above to calculate the electric field at $r = (a, b, c)$

Hint: Use symmetry to reduce to the case where $r = (a, 0, 0)$.

Maxwell's Equations:

$\vec{E}(x, y, z, t)$ - Electric field (at time t) ($R^4 \rightarrow R^3$)

$\vec{B}(x, y, z, t)$ - Magnetic field

$\rho(x, y, z, t)$ - charge density ($R^4 \rightarrow R$)

Gauss's Law:

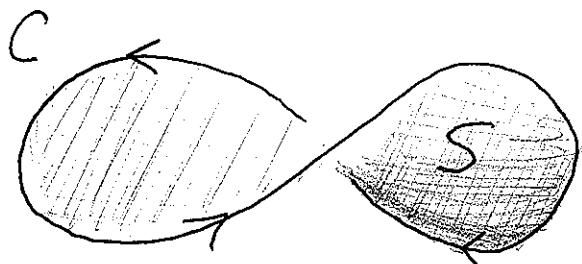
$$\operatorname{div} \vec{E} = \frac{\rho}{\epsilon_0}$$

$$\iint_{\partial R} \vec{E} \cdot \vec{n} \, dA = \iiint_R \rho \, dV$$

Gauss's Law for magnetic fields: [No magnetic monopoles.]

$$\operatorname{div} \vec{B} = 0 \quad \iint_{\partial R} (\vec{B} \cdot \vec{n}) \, dA = 0$$

Faraday's Law of Induction: A changing magnetic field induces a current in a loop of wire.



Now

$$\underbrace{\int_C \vec{E} \cdot d\vec{s}}_{\text{electromotive force aka voltage}} = -\frac{\partial}{\partial t} \iint_S \vec{B} \cdot \vec{n} \, dA$$

$$\int_C \vec{E} \cdot d\vec{s} = \iint_S (\operatorname{curl} \vec{E}) \cdot \vec{n} \, dA \quad \text{and so}$$

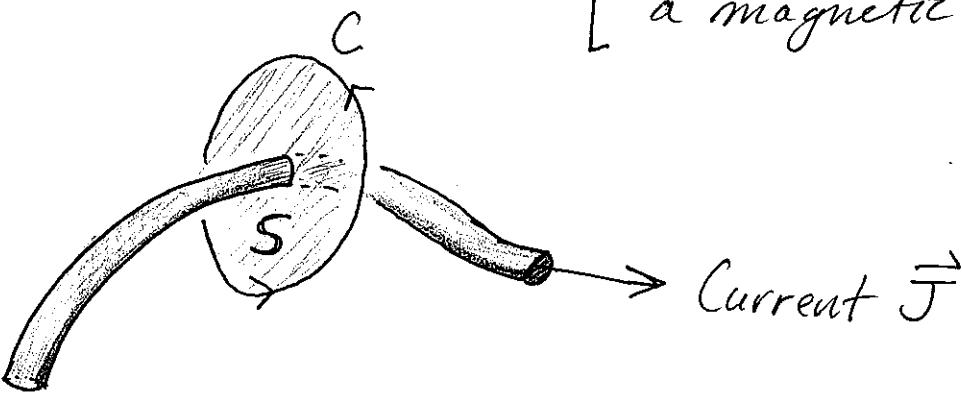
$$\operatorname{curl} \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

Unit check: ① $\vec{F} = Q\vec{E} \Rightarrow \vec{E}$ in $\frac{N}{C} = \frac{V}{m} \Rightarrow \int_C \vec{E} \cdot d\vec{r}$ is in Volts. ④

⑥ \vec{B} has units $T = \text{Tesla} = \frac{Vs}{m^2}$ \vec{n} = unitless

So $\iint_S \vec{B} \cdot \underbrace{\vec{n} dA}_{m^2}$ is in Vs $\Rightarrow \frac{\partial}{\partial t} \iint_S (\vec{B} \cdot \vec{n}) dA$ is in V.

Ampere's Circuital Law: [Current in a wire or a changing electric field induces a magnetic field.]



$$\int_C \vec{B} \cdot d\vec{r} = \mu_0 \iint_S (\vec{J} \cdot \vec{n}) dA + \epsilon_0 \mu_0 \frac{\partial}{\partial t} \iint_S (\vec{E} \cdot \vec{n}) dA$$

$$\iint_S (\text{curl } \vec{B}) \cdot \vec{n} dA$$

So $\boxed{\text{curl } \vec{B} = \mu_0 \vec{J} + \epsilon_0 \mu_0 \frac{\partial \vec{E}}{\partial t}}$

ϵ_0 = permittivity
of free space
= farads/m

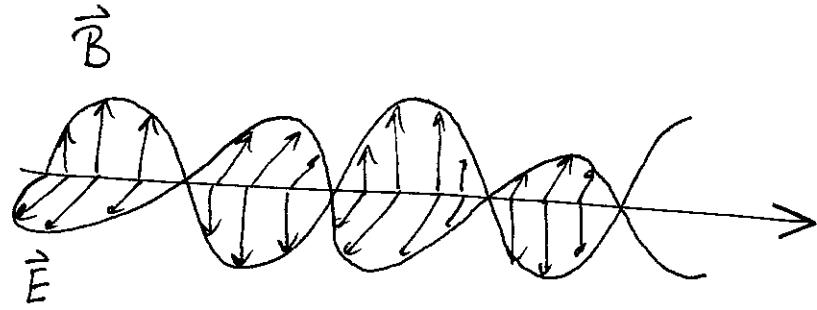
μ_0 = permeability of = N/A^2
free space

(5)

And there was light...

$C = \text{speed of light}$

$$= \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$



$$c = \omega \lambda \begin{matrix} \leftarrow \text{wave length} \\ \uparrow \text{freq} \end{matrix}$$

$$\vec{E} = (0, c \cdot \cos(2\pi(wt - x/\lambda)), 0)$$

$$\vec{B} = (0, 0, \cos(2\pi(wt - x/\lambda)))$$

Check: $\operatorname{curl} \vec{E} = \frac{\partial \vec{B}}{\partial t}$ $\operatorname{curl} \vec{B} = \epsilon_0 \mu_0 \frac{\partial \vec{E}}{\partial t}$
 $\operatorname{div} \vec{E} = 0$ $\operatorname{div} \vec{B} = 0.$

[Moral: Here are other applications of line and surface integrals, as well as the relations between them.]

If time remains: ① Multitude of integral theorems.

⑥ $\int_{\partial M} \omega = \int_M d\omega$