

Lecture 6: Today: Properties of matrix mult; determinants (finishing Section 1.4).

Next time: Cross products (Sect 1.5).

HW: On webpage: <http://durfield.info/241>

Last time: Matrix multiplication

$$\begin{matrix}
 & & \text{B} & & \\
 & \text{A} & & & \\
 \left. \begin{matrix} a \text{ rows} \\ \left(\begin{array}{|c|} \hline \\ \hline \end{array} \right) \\ b \text{ cols} \end{matrix} \right\} & & \left\{ \begin{matrix} \left(\begin{array}{|c|c|c|} \hline | & | & | \\ \hline \vec{v}_1 & \vec{v}_2 & \dots & \vec{v}_c \\ \hline | & | & | \end{array} \right) \\ c \text{ cols} \end{matrix} \right\} & b \text{ rows} = & \left\{ \begin{matrix} \left(\begin{array}{|c|c|c|} \hline | & | & | \\ \hline A\vec{v}_1 & A\vec{v}_2 & \dots & A\vec{v}_c \\ \hline | & | & | \end{array} \right) \\ c \text{ cols} \end{matrix} \right\} a \text{ rows}
 \end{matrix}$$

Ex: $\begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 4 & 2 \\ 2 & 1 \end{pmatrix}$

Properties: 1) $A(BC) = (AB)C$ (Associative)

2) $A(B+C) = AB + AC$ (Distributive)
 $(A+B)C = AC + BC$

However, typically we don't have $AB = BA$!

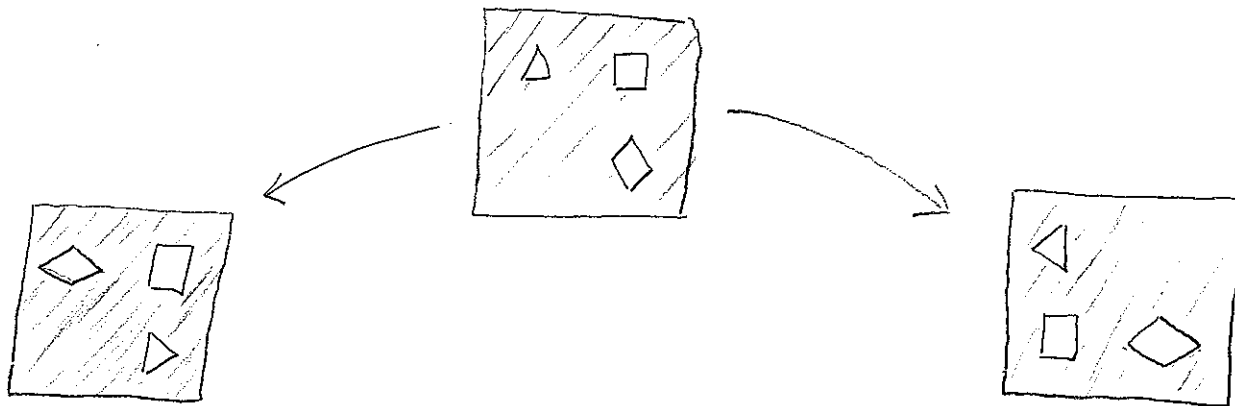
Ex: $A = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ $B = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ $\left\{ \begin{array}{l} AB = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \\ BA = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix} \end{array} \right.$

these differ!

In terms of linear transformations

$F_A: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ rotation by 90° counterclockwise

$F_B: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ reflection in the x -axis



$F_{AB} = F_A \circ F_B =$ reflection followed by rotation

$F_{BA} = F_B \circ F_A =$ rotation followed by reflection

How do these differ? Rotation by 180° . What's the matrix for that? $\begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} = -I_2$ so

$$(\text{rot}_{90^\circ} \circ \text{ref}) = (\text{rot}_{180^\circ} \circ \text{ref} \circ \text{rot}_{90^\circ}) \iff AB = -BA$$

Determinants: (square matrix) \rightarrow (number)

$$\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc \quad \text{Ex: } \det \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} = 4 - 1 = 3$$

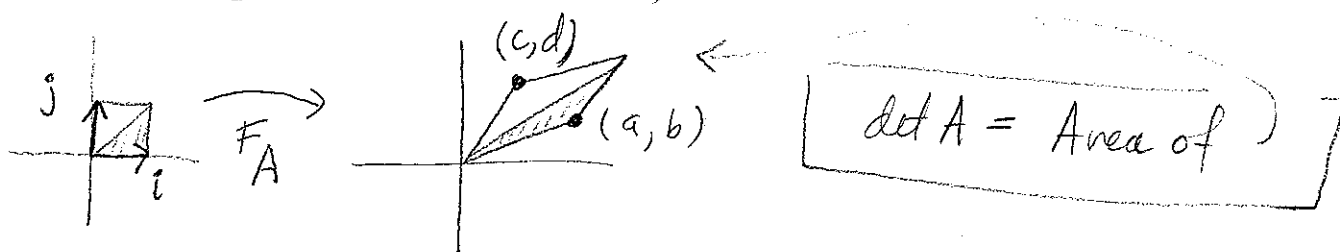
$$\det \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} = a_{11} \det \begin{pmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{pmatrix} - a_{12} \det \begin{pmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{pmatrix} + a_{13} \det \begin{pmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{pmatrix}$$

Ex:

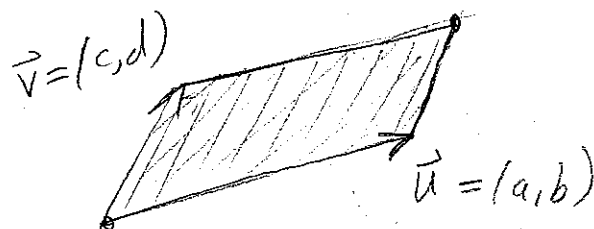
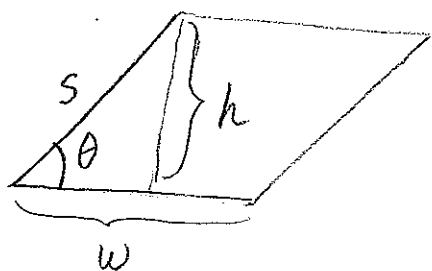
↙ means $\det \begin{pmatrix} z & 1 \\ 1 & 0 \end{pmatrix}$

$$\det \begin{pmatrix} 1 & -1 & 0 \\ 0 & 2 & 1 \\ 3 & 1 & 0 \end{pmatrix} = 1 \cdot \begin{vmatrix} 2 & 1 \\ 1 & 0 \end{vmatrix} + \begin{vmatrix} 2 & 1 \\ 3 & 0 \end{vmatrix} = -1 - 3 = -4$$

Geometric meaning: $A = \begin{pmatrix} a & c \\ b & d \end{pmatrix}$



Area of a parallelogram = $wh = ws \sin \theta$



$$\text{Area} = \|\vec{u}\| \|\vec{v}\| \sin \theta$$

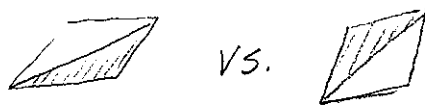
This formula for area looks like our formula for $\vec{u} \cdot \vec{v}$ except we have \sin not \cos . [How can we go from one to the other?]

$$\begin{aligned}
 \text{Area}^2 &= \|\vec{u}\|^2 \|\vec{v}\|^2 \sin^2 \theta = \|\vec{u}\|^2 \|\vec{v}\|^2 (1 - \cos^2 \theta) \\
 &= \|\vec{u}\|^2 \|\vec{v}\|^2 - (\vec{u} \cdot \vec{v})^2 = (a^2 + b^2)(c^2 + d^2) - (ac + bd)^2 \\
 &= \underline{a^2 c^2} + a^2 d^2 + b^2 c^2 + \underline{b^2 d^2} - \underline{a^2 c^2} - \underline{b^2 d^2} - 2abcd \\
 &= (ad - bc)^2 = (\det A)^2
 \end{aligned}$$

Hey, but $\det A$ can be negative!, e.g. $\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

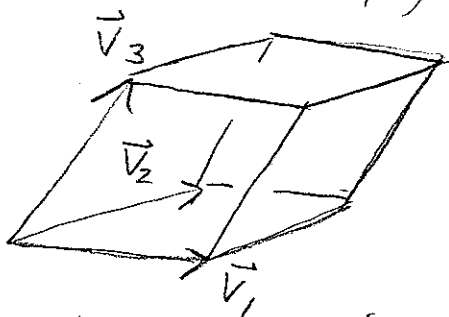
So really $|\det A| = \text{Area of } \square$

and the determinant is negative when F_A flips the square over.

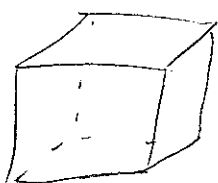


For similar reasons, if $A = \begin{pmatrix} | & | & | \\ v_1 & v_2 & v_3 \\ | & | & | \end{pmatrix}$ is 3×3 then

$\det A = \text{Volume of}$



which is the image of the unit cube



under F_A .

If time remains, explain

$$\det AB = (\det A)(\det B)$$