

Lecture 49: Differential Forms (§8.4)

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This week: §8.4 Note: ICES online.

So far, we've a bunch of theorems relating integrals over boundaries with integrals of derivatives over regions.

These are all the same if \leftarrow [div, grad, curl...]
we use the language of differential forms: \leftarrow very 3-dim'l.

|| ω a k -form defined on a region R of dimension $k+1$.
Then: $\int_{\partial R} \omega = \int_R d\omega$

The goal of this week is to explain what this means.

[Applications: "repackaging" Maxwell's equations; fixing the Steiner A.]

A k -form is something which can be integrated over a k -dimensional object. ["the bit after the integral sign."]

Ex: 0-form: $f(x)$...

1-form: $f(x) dx$ $f(x,y,z) ds$ \perp \int

2-form: $f(x,y) dx dy$ dA  

[3-form: $f(x,y,z) dx dy dz$ dV]

0-forms: A 0-form on U in \mathbb{R}^n is just a function: $f: U \rightarrow \mathbb{R}$

1-form: A 1-form on U in \mathbb{R}^3 is something of the form

$$\alpha = f(x,y,z) dx + g(x,y,z) dy + h(x,y,z) dz$$

where $f, g, h: U \rightarrow \mathbb{R}$ are functions.

for the moment

these are formal

symbols, [playing

a role like $\vec{i}, \vec{j}, \vec{k}$ for defining vector fields.]

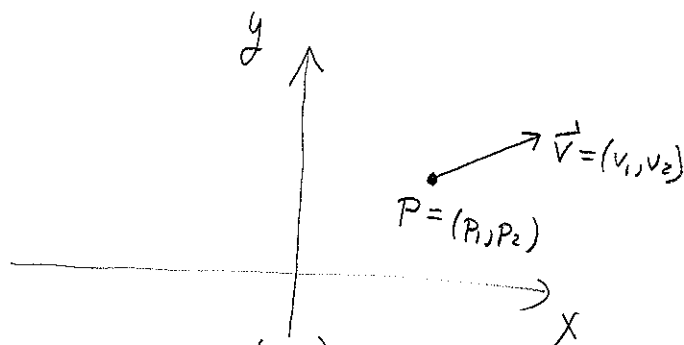
Ex: $\alpha = y^2 dx + (x+y) dy$ a 1-form on \mathbb{R}^2

[Remind how this looks like something you can integrate over a path.]

What a 1-form does: Eats vectors

$$\text{if } \alpha = f(x,y) dx + g(x,y) dy$$

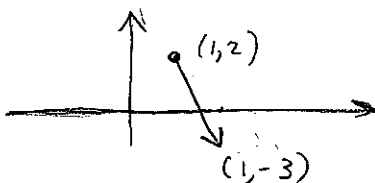
then



$$\alpha_P(\vec{V}) = f(P) v_1 + g(P) v_2 = (f(P) \ g(P)) \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$$

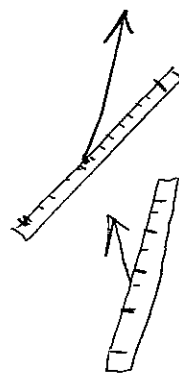
Ex: α as above

$$\alpha_{(1,2)}(1, -3) = (4 \ 3) \begin{pmatrix} 1 \\ -3 \end{pmatrix} = 4 - 9 = -5$$

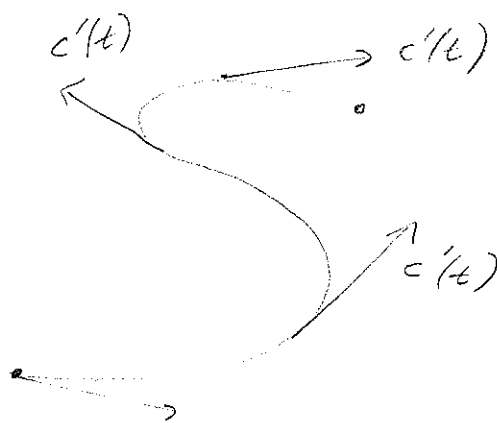
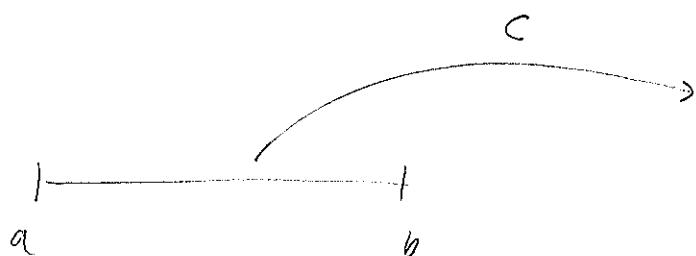


Thus α assigns to each point in the plane

a linear transformation $\mathbb{R}^2 \rightarrow \mathbb{R}$. We can think of this as a "ruler" at each point which we use to measure vectors.



We can integrate a 1-form over a curve C like this



$$\int_C \alpha = \int_a^b \alpha_{c(t)}(c'(t)) dt$$

$$= \int_a^b (f(c(t))c_1'(t) + g(c(t))c_2'(t)) dt$$

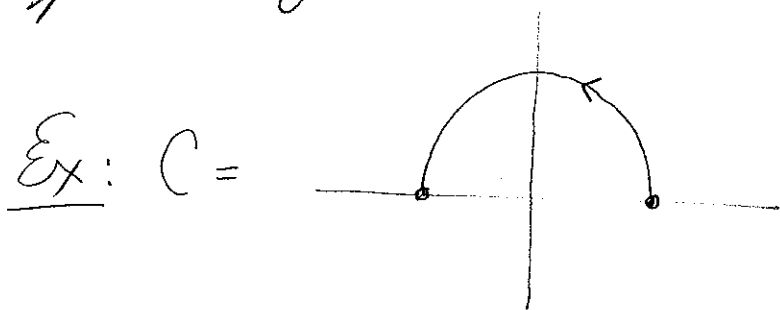
where

$$\alpha = f(x,y) dx + g(x,y) dy$$

and

$$c(t) = (c_1(t), c_2(t)).$$

As always, this doesn't depend on the parameterization.



$$C(t) = (\cos t, \sin t) \\ 0 \leq t \leq \pi$$

$$\alpha = y^2 dx + (x+y) dy$$

$$\int \alpha = \int_0^\pi \alpha_{C(t)}(C'(t)) dt = \int_0^\pi (\sin^2 t, \cos t + \sin t) \begin{pmatrix} -\sin t \\ \cos t \end{pmatrix} dt$$

$$= \int_0^\pi -\sin^3 t + \cos^2 t + \sin t \cos t dt =$$

What's going on here?

- 1) Before, we needed two things to integrate over a curve: a function and "ds". The 1-form α combines these 2 into one package.
- 2) A 1-form can be thought of as coming from a vector field \vec{F} where
$$\alpha_p(\vec{v}) = \vec{F}(p) \cdot \vec{v}$$
 Then
$$\int_C \alpha = \int_C \vec{F} \cdot ds.$$